

## CS Q-LEAP<sup>™</sup> P-SINE with SE-13

primary calibration system with vibration exciter

	$\sim$ Typical DUT	
HERO <sup>™</sup> vibration controller incl. signal conditioners	<ul> <li>heavy seismic sensors (seismometers)</li> <li>geophones for structure/building vibration measurement</li> </ul>	
CS Q-LEAP <sup>™</sup> software • sine calibration • sine sweep • vibration measurement • vibration generation • more on demand	<ul> <li>accelerometers and vibration velocity sensors for the very low frequency range</li> <li>Standards</li> </ul>	
SE-13 vibration exciter for vertical excitation incl. power amplifier	<ul> <li>ISO 16063-11: primary calibration of vibration transducers by laser interferometry</li> <li>ISO 16063 - 21: calibration of vibration transducers by comparison to a reference transducer</li> <li>ISO 17025: general requirements for the competence of testing and calibration laboratories</li> <li>DIN 45669: sensors for measurement of vibration immission</li> </ul>	
all-digital laser vibrometer incl. vibration isolation and positioning device for the laser head		

## ★ Key features

	Frequency range 0.1 Hz400 Hz
	Traceable to PTB (German National Metrology Laboratory)
-6-11	calibration of vibration sensors, seismic sensors and geophones
	integrated sensor database
	integrated software for the generation of calibration certificates (print, PDF,), easy data exchange with applications like ERP systems or measuring equipment databases

## 😥 Technical data

Frequency range	0.1 Hz400 Hz
Displacement <sup>1)</sup> , max.	25 mm (1 in)
Velocity <sup>2)</sup> , max.	300 mm/s (15.8 in/s)
Acceleration <sup>2) 3)</sup> , max.	60 m/s² (6 g <sub>n</sub> ) peak
Operation	vertical
Moving element weight	8 kg (18 lbs)
Payload, max.	50 kg (110 lbs)
Table size	Ø 350 mm (14 in)

1) Recommended operation range peak-peak; mechanical stop at 32 mm (1.3 in)

2) Peak sine

3) Interval mode of operation

Frequency range		Max. recommended	Expanded measurement uncertainty <sup>1)</sup>
from	to	payload	magnitude <sup>2)</sup> / phase <sup>3)</sup>
0.1 Hz	0.4 Hz	50 kg (110 lbs)	1.5 % / 1.5°
> 0.4 Hz	16 Hz		0.7 % / 1.0°
> 16 Hz	40 Hz		1.5 % / 1.5°
> 40 Hz	100 Hz	20 kg (44 lbs)	2.0 % / 2.0°
> 100 Hz	400 Hz	10 kg (22 lbs)	2.0 % / 2.0°
Reference frequencies: 1 Hz / 4 Hz / 8 Hz / 16 Hz		25 kg (55 lbs)	0.7 % / 1.0°

Recommended excitation amplitudes (peak values)		
Minimum	0.1 Hz400 Hz: 1.0 mm/s 1 Hz ref. freq.: 0.2 mm/s	
Maximum (high payload) <sup>4)</sup> (displacement, velocity, acceleration)	<ul> <li>10 mm in the range of 0.1 Hz4 Hz</li> <li>250 mm/s in the range of 4 Hz6.5 Hz</li> <li>10 m/s<sup>2</sup> in the range of 6.5 Hz400 Hz</li> </ul>	
<b>Maximum (low payload)</b> <sup>5)</sup> (displacement, velocity, acceleration)	10 mm in the range of 0.1 Hz4 Hz 250 mm/s in the range of 4 Hz25 Hz 40 m/s <sup>2</sup> in the range of 25 Hz120 Hz 40 m/s <sup>2</sup> 25 m/s <sup>2</sup> in the range of 120 Hz400 Hz	

 Determined according to GUM (JCGM 100 "Evaluation of measurement data - Guide to the expression of uncertainty in measurement") with k = 2 (coverage factor) for the best possible device under test (DUT). Other devices that are not assumed as ideal must be evaluated with individual contributions.

The measurement uncertainty is specified for the best possible DUT: "Nanometrics Trillium Compact" (plus its mounting adapter) in two configurations: first the DUT and secondly the DUT with additional dummy mass. Best uncertainty values only valid for symmetric centered mounting of the DUT and the mass with a center of gravity <80 mm at 35 kg above exciter table. Any other type of DUT can be calibrated. But they must meet the maximum payload limits given by the data sheet of the vibration exciter. Measurement uncertainties need to be determined individually, especially for frequencies above 20 Hz.

2) Valid for electrical sensor signals  $\geq$  (1 mV or 1 pC)

3) Requires optional software

4) Maximum vibration amplitude for maximum payload (DUT)

5) Maximum vibration amplitude without any payload (DUT)